

# A Fitted Numerical Method for Singularly Perturbed Integro-Differential Equations with Delay

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**Abstract** – This study deals with the singularly perturbed initial value problems for a quasilinear first-order integro-differential equations with delay. A numerical method is generated on a grid that is constructed adaptively from a knowledge of the exact solution, which involves appropriate piecewise-uniform mesh on each time subinterval. An error analysis shows that the discrete solutions are uniformly convergent with respect to the perturbation parameter. The parameter uniform convergence is confirmed by numerical computations.

**Keywords** – Singularly perturbed problems, integro-differential equation, difference schemes, uniformly convergent.

## I. Introduction

Consider an initial value problem for the linear second order singularly perturbed integro-differential equation with delay

$$eu'(t) + f(t, u(t), u(t-r)) + \int_0^t K(t, s)u(s-r)ds = 0 \quad t \in I, \quad (1)$$

$$u(t) = j(t), \quad t \in I_0, \quad (2)$$

where  $I = (0, T], I_0 = (-r, 0]$ .  $0 < e \leq 1$  is the perturbation parameter,  $a(t) \geq a > 0$ ,  $f(t)$  and  $j(t)$  are given sufficiently smooth functions satisfying certain regularity conditions to be specified and  $r$  is a constant delay.

Volterra delay-integro-differential equations (VDIDEs) arise widely in scientific fields such as biology, ecology, medicine and physics. This class of equations plays an important role in modelling diverse problems of engineering and natural science, and hence has led researchers to develop a theory and numerical analysis for VDIDEs.

Delay differential equations play an important role in the mathematical modelling of various practical phenomena in the biosciences and control theory. Any system involving a feedback control will almost always involve time delays. These arise because a finite time is required to sense information and then react to it. A singularly perturbed delay differential equation is an ordinary differential equation in which the highest derivative is multiplied by a small parameter and involving at least one delay term [1-4]. Such problems arise frequently in the mathematical modelling of various practical phenomena, for example, in the modelling of several physical and biological phenomena like the optically bistable devices [5], description of the human pupil-light reflex [6], a variety of models for

physiological processes or diseases and variational problems in control theory where they provide the best and in many cases the only realistic simulation of the observed phenomena [7]. An overview of numerical treatment for first and second order singularly perturbed delay differential equations, may be obtained in [8-15] (see, also references therein).

The numerical analysis of singular perturbation cases has always been far from trivial because of the boundary layer behavior of the solution. Such problems undergo rapid changes within very thin layers near the boundary or inside the problem domain. It is well known that standard numerical methods for solving singular perturbation problems do not give satisfactory result when the perturbation parameter is sufficiently small. Therefore, it is important to develop suitable numerical methods for these problems, whose accuracy does not depend on the perturbation parameter, i.e. methods that are uniformly convergent with respect to the perturbation parameter [16-19].

In a singularly perturbed delay differential equation, one encounters with two difficulties, one is because of occurrence of the delay term and another one is due to presence of perturbation

parameter. To overcome the first difficulty, we employed the numerical method of steps [2] for the delay argument which converted the problem to a initial value problem for a singularly perturbed differential equation. Then we constructed a numerical scheme based on finite difference method on non uniform Shishkin mesh for the numerical solution.

In the present study we discretize the problem (1)-(2) using a numerical method, which is composed of a fitted difference scheme on piecewise uniform Shishkin mesh on each time-subinterval.

## II. Discretization and Mesh

In this section, we construct a numerical scheme for solving the initial value problem (1)-(2).

We propose the following difference scheme for approximation (1)-(2)

$$L_N y_i = e \frac{y_i - y_{i-1}}{h} + f(t_i, y_i, y_{i-N}) \quad , \quad i = 1, 2, \dots, N_0, \quad (3)$$

$$+ \sum_{j=0}^{i-1} h_{j+1} K(t_i, t_j) y_{j-1} = 0,$$

$$y_i = j_i, \quad -N \leq i \leq 0, \quad (4)$$

The difference scheme (3)-(4), in order to be  $e$ -uniform convergent, we will use the Shishkin mesh. For the even number  $N$ , the piecewise uniform mesh  $W_{N,p}$  divides each of the interval  $[r_{p-1}, S_p]$  and  $[S_p, r_p]$  into  $N/2$  equidistant subintervals, where the transition point  $S_p$ , which separates the fine and coarse portions of the mesh is obtained by  $S_p = r_{p-1} + \min\{r/2, a^{-1}e \ln N\}$ .

### III. Convergence Analysis

We now estimate the approximate error  $z_i = y_i - u_i$ , which satisfies the discrete problem

$$L_N y_i = R_i, \quad i = 0, 1, 2, \dots, N_0, \quad (5)$$

$$z_i = 0, \quad -N \leq i \leq 0, \quad (6)$$

where  $R_i$  is the truncation errors.

**Theorem.** The continuously differentiable function  $f(t, u, v)$  satisfies the regularity conditions and the derivative  $f(t, u, v)$  is bounded for

$\frac{\partial}{\partial t} f(t, u, v)$  is bounded for given interval. Then the following estimate holds

$$|y_i - u_i| \leq CN^{-1} \ln N, \quad 0 \leq i \leq N_0,$$

where  $u_i$  is exact solution of the problem (1)-(2) and  $u_i$  is the solution of the problem (3)-(4).

### IV. Numerical Results

In this section, a simple numerical example is devised to verify the validity for the proposed method.

Consider the test problem

$$eu'(t) + u(t) + u(t-1) + \int_0^t u(s-1)ds = 0, \quad t \in (0, 2],$$

$$u(t) = 1, \quad -1 \leq t \leq 0.$$

The exact solution given by

$$u(t) = \begin{cases} e^{-t}, & t \in [0, 1] \\ \frac{1}{e^2} e^{-t/e} [e e^{2/e} - e e^{(t+1)/e} - e^{t/e} (t-e) e^2 \\ + e^{1/e} (-1+t+e - et + 2e^2 - e^3)], & t \in [1, 2] \end{cases}$$

We define the exact errors  $e^{N,p}$  as follows

$$e^{N,p} = \|y - u\|_{w_{N,p}}, \quad p = 1, 2$$

where  $y$  is the numerical approximation of  $u$  for values of  $N$  and  $e$ .

Maximum errors and rates of convergence.

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Maximum errors and rates of convergence.

$e$	N=64	N=128	N=256
$2^{-2}$	<b>0,01328142</b>	<b>0,0640103</b>	<b>0,0322010</b>
$2^{-8}$	<b>0,01361427</b>	<b>0,0692344</b>	<b>0,0330323</b>
$2^{-16}$	<b>0,01482356</b>	<b>0,0713864</b>	<b>0,0342657</b>

### Conclusion

In this study we have presented a numerical approach to solve a quasilinear singularly perturbed first-order integro-differential equation with delay. We proposed a fitted difference scheme on piecewise-uniform Shishkin mesh on each time subinterval. We have shown that the method displays uniform convergence with respect to the perturbation parameter for numerical approximation of the solution.

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