чується відповідним вибором порядку числової схеми та кроку дискретизації. Наведена модифікація методу є його подальшим удосконаленням у підвищенні точності і зменшенні обчислювальних витрат.

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## MAGNETIC FIELD AND IMPEDANCE OF A CIRCUIT WITH GROUND RETURN FOR A TWO-LAYER OVERHEAD CONDUCTOR

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For a circuit with ground return consisting of a long rectilinear overhead conductor the vector magnetic potential is introduced. Transformation of the differential equations describing the magnetic potential by means of Fourrier's transformation yields the vector potential in the form of an analytical formula. Next, the magnetic field strength represented by improper integrals is determined. Appropriate representation of those calculations reduces them to the calculation of Laplace's transformation, thus yielding analytical formulae describing the magnetic field in the circuit with ground return.

The impedance of a circuit with ground return for a two-layer overhead conductor is represented as the total of external and internal impedances. The external impedance is determined using the vector magnetic potential to compute the induced electric field strength. The internal impedance of the conductor is determined using the solution of the Helmholtz's equation for electric field strength.

Finally a computer simulation in Delphi of the discussed question is presented.

**Introduction.** A circuit with ground return consists of a two-layer overhead conductor placed at the height of  $y_k$ . – Fig. 1. In the conductor sinuously alternating current of pulsation  $\omega$  and complex r.m.s. value I is forced. The conductor has one of its terminals grounded.

The cylindrical conductor is two-layered with a core of radius  $R_1$  and conductivity  $\gamma_1$ , and with an external layer of radius  $R_1$  and  $R_2$  and conductivity  $\gamma_2$  – Fig. 2. It is parallel to the ground surface.



Fig. 1. A circuit with ground return

Fig. 2. Two-layer conductor with current I

Moreover, we assume that the ground constitutes a homogenous environment of magnetic permittivity  $\mu_0$  and constant conductivity  $\gamma$ , and we assume that the ground surface is a plane.

If we leave out phenomena taking place at the ends of the system, the electromagnetic field in the system in question is two-dimensional and has the same form in all planes perpendicular to the conductor axis, i.e. it is a function of two variables *x* and *y*. Magnetic vector potential is used in the analysis of the magnetic field.

Impedance of the loop with ground return equals the external impedance  $Z_z$  and the internal impedance of the conductor  $Z_w$ . Then the impedance of the loop with ground return per unit length

$$Z = Z_z + Z_w$$
 (1)

**Vector potential.** In the system depicted in Fig. 1 the magnetic vector potential is parallel to the conductor axis that is  $A(x, y) = \mathbf{1}_z A(x, y)$ . In Ref. [2] M. Krakowski gives the Poisson's equation (Formula (11.83), p.257) in area "1" above the ground and Helmholtz's equation (Formula (11.84), p.258) in area "2", that is in the ground. According to the denotations used in fig. 1, in particular having introduced distance  $x_k$ , these equations are of the following form:

$$\frac{\partial^2 A_1(x, y)}{\partial x^2} + \frac{\partial^2 A_1(x, y)}{\partial y^2} = -\mu_0 I \,\delta(x - x_k) \,\delta(y - y_k), \tag{2}$$

and

$$\frac{\partial^2 A_2(x,y)}{\partial x^2} + \frac{\partial^2 A_2(x,y)}{\partial y^2} = \beta^2 A_2(x,y), \qquad (2a)$$

where  $\delta(x - x_k)$  and  $\delta(y - y_k)$  are Dirac's discrete functions, while

$$\beta^2 = j \overline{\omega} \mu_0 \gamma. \tag{2b}$$

Transformation of each following term in equations (2) and (2a) by means of Fourrier's transform in relation to variable x, then formulation and transformation of boundary\_conditions, finally determination of inverse Fourrier's transform according to the way applied in Ref. [2,

p. 258–260], yields the vector potential in area "1" (the formula is similar to formula (11.59) in Ref. [2, p.260].

$$A_{1}(x,y) = \frac{\mu_{0}I}{\pi} \left[ Q_{1} + \frac{1}{4} \ln \frac{(x-x_{k})^{2} + (y+y_{k})^{2}}{(x-x_{k})^{2} + (y-y_{k})^{2}} \right],$$
(3)

where function  $Q_1$  can be written as

$$Q_1 = \int_0^\infty \frac{e^{-\varpi(y+y_k)} cos[\varpi(x-x_k)]}{\varpi + \sqrt{\varpi^2 + \beta^2}} d\varpi.$$
(3a)

After the substitution:

$$\begin{array}{l} \overline{\omega} = \alpha \, u, & d\overline{\omega} = \alpha \, du, \\ \alpha = \sqrt{\overline{\omega} \, \mu_0 \, \gamma}, & \beta = \sqrt{j} \, \alpha \end{array} \right\}$$

$$(4)$$

and

$$p = \alpha (y + y_k), q = \alpha (x - x_k)$$
(4a)

the function  $Q_1$  can be written as

$$Q_1(p,q) = \int_0^\infty \frac{e^{-pu} \cos qu}{u + \sqrt{u^2 + j}} \, du \,.$$
(5)

**Magnetic field.** The magnetic field in area "1" (above the ground) is computed from equation [4]

$$H_{1}(x, y) = \frac{1}{\mu_{0}} \operatorname{rot} A_{1}(x, y) = \mathbf{1}_{x} H_{1x}(x, y) + \mathbf{1}_{y} H_{1y}(x, y), \qquad (6)$$

where the components of the magnetic field strength

$$H_{1x}(x,y) = \frac{1}{\mu_0} \frac{\partial A_1(x,y)}{\partial y} = \frac{\alpha}{\pi} I \, dQ_{1p}[\alpha(y+y_k),\alpha(x-x_k)] + \frac{1}{2\pi} I \left[ \frac{y+y_k}{(x-x_k)^2 + (y+y_k)^2} - \frac{y-y_k}{(x-x_k)^2 + (y-y_k)^2} \right]$$
(6a)

and

$$H_{1y}(x,y) = -\frac{1}{\mu_0} \frac{\partial A_1(x,y)}{\partial x} = -\frac{\alpha}{\pi} I \, dQ_{1q} [\alpha(y+y_k), \alpha(x-x_k)] - \frac{1}{2\pi} I \left[ \frac{x-x_k}{(x-x_k)^2 + (y+y_k)^2} - \frac{x-x_k}{(x-x_k)^2 + (y-y_k)^2} \right]$$
(6b)  
(6c) the derivative of function  $Q_1$  in relation to variable,  $\alpha$ 

In formula (6a) the derivative of function  $Q_1$  in relation to variable q

$$dQ_{1q}(p,q) = \frac{\partial Q_1(p,q)}{\partial q} = -\int_0^\infty \frac{ue^{-pu}sinqu}{u+\sqrt{u^2+j}} du, \qquad (6c)$$

while in (6b) the derivative of function  $Q_1$  in relation to variable p

$$dQ_{1p}(p,q) = \frac{\partial Q_1(p,q)}{\partial p} = -\int_0^\infty \frac{ue^{-pu}cosqu}{u+\sqrt{u^2+j}} du.$$
(6d)

Substitution into formulae (6c) and (6d) of the following

$$\sin qu = \frac{1}{2j} (e^{jqu} - e^{-jqu}) 
\cos qu = \frac{1}{2} (e^{jqu} + e^{-jqu}) 
\frac{-u}{u + \sqrt{u^2 + j}} = j (u\sqrt{u^2 + j} - u^2)$$
(7)

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yields respectively

$$dQ_{1q}(p,q) = \frac{1}{2} \left\{ \int_{0}^{\infty} (u\sqrt{u^{2}+j} - u^{2}) e^{-su} du \right|_{s=p-jq} - \int_{0}^{\infty} (u\sqrt{u^{2}+j} - u^{2}) e^{-su} du \Big|_{s=p+jq} \right\}, \quad (8)$$

$$dQ_{1p}(p,q) = \frac{1}{2} j \left\{ \int_{0}^{\infty} (u\sqrt{u^{2}+j} - u^{2}) e^{-su} du \right|_{s=p-jq} + \int_{0}^{\infty} (u\sqrt{u^{2}+j} - u^{2}) e^{-su} du \right|_{s=p+jq} \right\}.$$
 (9)

For  $Re\{s\} = p > 0$  the integral from formulas (8) and (9) is the Laplace's transform of the integrand, i.e

$$\int_{0}^{\infty} (u\sqrt{u^{2}+j}-u^{2}) e^{-su} du = L\left\{u\sqrt{u^{2}+j}-u^{2}\right\} = L\left\{u\sqrt{u^{2}+j}\right\} - L\left\{u^{2}\right\}.$$
(10)

Laplace's transform from function  $u^2$  and function  $u\sqrt{u^2 + j}$  is calculated by Mathematica 3.0 program – Ref. [6].

Thus the components of the magnetic field strength are written as analytical formulas which enables us to calculate vector  $H_1(x, y)$  in any point of area "1" above the ground

**External impedance.** External impedance  $Z_z$  per unit length of a loop with ground return is determined with assumption that the conductor in the circuit with ground return from Fig. 1 is of infinite length. Then the vector magnetic potential in area ",1" above the ground is given by formula (3).

External impedance of the conductor is given (formula (8.76) in Ref. [4, p.168]) by the following formula:

$$Z_z = -\frac{\int \boldsymbol{E}_{in1} \cdot d\boldsymbol{l}}{I},\tag{11}$$

where  $E_{in}$  is the strength of electric field induced due to time changes of the external magnetic field, while the integration curve is the line *C* on the conductor surface.

The induced electric field strength (for  $A_1 = \mathbf{1}_z A_1$ )

$$\boldsymbol{E}_{in1} = -j\boldsymbol{\sigma} \boldsymbol{A}_1 = -j\boldsymbol{\sigma} \boldsymbol{A}_1 \boldsymbol{1}_z = \boldsymbol{E}_{in1z} \boldsymbol{1}_z, \qquad (12)$$

from where after the substitution of formula (3) one obtains

$$E_{in1z}(x,y) = -\frac{\varpi\mu_0 I}{\pi} \left[ Q(p,q + \frac{j}{4} \ln \frac{(x - x_k)^2 + (y + y_k)^2}{(x - x_k)^2 + (y - y_k)^2} \right],$$
(13)

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where function

$$Q(p,q) = j Q_1(p,q) = j \int_0^\infty \frac{e^{-pu} \cos qu}{u + \sqrt{u^2 + j}} du,$$
(13a)

i.e. that the function is determined by the formula given by M.Krakowski in Ref. [4 (Formula (9.137), p. 207].

Substitution into formula (13a) of the following

$$\cos qu = \frac{1}{2} (e^{jqu} + e^{-jqu}) \\
\frac{1}{u + \sqrt{u^2 + j}} = -j(\sqrt{u^2 + j} - u)$$
(14)

yields function Q given by the formula

$$Q(p,q) = \frac{1}{2} \left\{ \int_{0}^{\infty} (\sqrt{u^{2} + j} - u) e^{-su} du \bigg|_{s=p-jq} - \int_{0}^{\infty} (\sqrt{u^{2} + j} - u) e^{-su} du \bigg|_{s=p+jq} \right\}.$$
 (15)

For  $Re{s} = p > 0$  the integral in formula (15) is the Laplace's transform of the integrand, i.e.

$$\int_{0}^{\infty} (\sqrt{u^{2} + j} - u) e^{-su} du = L \left\{ \sqrt{u^{2} + j} - u \right\} = L \left\{ \sqrt{u^{2} + j} \right\} - L \left\{ u \right\}.$$
(16)

Laplace's transform from function u and function  $\sqrt{u^2 + j}$  is calculated by Mathematica 3.0 program – Ref. [6].

According to the formula (11) and assuming that  $2y_k \rangle \rangle R_2$ , external impedance of the conductor per unit length is given by the formula

$$Z_{z} = -\frac{E_{in1z}(x_{k}, y_{k} - R_{2})}{I} = \frac{\overline{\omega}\mu_{0}}{\pi} \left[ Q(2\alpha \ y_{k}, 0) + \frac{j}{2} \ln \frac{2y_{k}}{R_{2}} \right].$$
(17)

**Internal impedance.** Electric field strengths in a two-layer conductor are determined by taking into consideration the given current I. In Ref. [2] the authors have proved that these fields depend on the variable r of the cylindrical coordinate system and are given by following formulas:

- for  $0 \le r \le R_1$ 

$$\boldsymbol{E}_{1}(r) = \boldsymbol{1}_{z} E_{1}(r) = \boldsymbol{1}_{z} I C_{1} J_{0}(\boldsymbol{\beta}_{1} r), \qquad (18)$$

where  $\beta_1 = \sqrt{-j\varpi\mu_1\gamma_1}$ ,

 $- \text{ for } R_1 \le r \le R_2$ 

$$\boldsymbol{E}_{2}(r) = \mathbf{1}_{z} \boldsymbol{E}_{2}(r) = \mathbf{1}_{z} \boldsymbol{I} \left[ \boldsymbol{C}_{2} \, \mathbf{J}_{0}(\boldsymbol{\beta}_{2} \, r) + \boldsymbol{C}_{3} \, \mathbf{N}_{0}(\boldsymbol{\beta}_{2} \, r) \right], \tag{18a}$$

where  $\beta_2 = \sqrt{-j\varpi\mu_2\gamma_2}$ ,

 $J_0(\beta r)$ ,  $N_0(\beta r)$  – Besel functions of first and second kind, 0 order,

Constants  $C_1$ ,  $C_2$  and  $C_3$  are obtained form the following system of equations:

$$\begin{bmatrix} J_{0}(\beta_{1} R_{1}) & -J_{0}(\beta_{2} R_{1}) & -N_{0}(\beta_{2} R_{1}) \\ -\frac{\gamma_{1}}{\beta_{1}} J_{0}'(\beta_{1} R_{1}) & \frac{\gamma_{2}}{\beta_{2}} J_{0}'(\beta_{2} R_{1}) & \frac{\gamma_{2}}{\beta_{2}} N_{0}'(\beta_{2} R_{1}) \\ 0 & \frac{\gamma_{2}}{\beta_{2}} J_{0}'(\beta_{2} R_{2}) & \frac{\gamma_{2}}{\beta_{2}} N_{0}'(\beta_{2} R_{2}) \end{bmatrix} \cdot \begin{bmatrix} C_{1} \\ C_{2} \\ C_{3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \frac{1}{2\pi R_{2}} \end{bmatrix}.$$
(18b)

The internal impedance of the conductor segment equals the quotient of the complex voltage value along the line on that segment surface divided by the complex value of the current in the conductor (Ref. [4], formula (8.77), p. 167):

$$Z_{wl} = \frac{\int E_2(r = R_2) \cdot dl}{I}.$$
(19)

Thus the internal impedance per unit length of the conductor

 $Z_{w} = C_{2} J_{0}(\beta_{2} R_{2}) + C_{3} N_{0}(\beta_{2} R_{2}).$ (19a)

**Conclusions.** To enable the determination of the magnetic field and impedance of a circuit with ground return for a two-layer overhead conductor a project in Delphi has been elaborated – Fig. 3.

Select the con	ductor typ	e Option:	AFL-20-	-840	Computational options		
AFL-20-775 Current module in [A] 1000 AFL-20-840 AFL-8-350 Current phase [stop] 0					Sround return impedance		
Select the number	of conduc	ctors in a s	heal 1	*	Graph of	magnetic field stre	ength at the height y
Conductor number	* [m]	y [m]	I IAJ	f [stop]	minX [m]	y [m]	maxX [m]
Conductor 1	0	6	1000,00	0,00	-15,1	1.8	15,1
					L Graph of t	he magnetic field s	trength for a given *
1000000		-			minY [m]	× [m]	maxY [m]
[mpedance of a circuit with ground return [mili Uhm/m] Z = 0,08310 + j 0,68767					0,0	2,0	12,0

Fig. 3. Form of a numerical simulator for determination of the impedance of a circuit with ground return

For actual computations of the magnetic field we have chosen a two-layer conductor AFL-20-840 placed at the height of  $y_k = 6$  m. Fig. 4 depict the distribution of magnetic field strengths along some chosen straight line in the system of the two-layer conductor-ground.



Fig. 4. Distribution of the magnetic field along the straight line y = 1,8 m;  $y_k = 6 m$ , I = 1 kA.

Table

	Type of conductor	Impedance in $m\Omega \cdot m^{-1}$		
1	AFL-20-670	0,09171 + j 0,69503		
2	AFL-20-840	0,08310 + j 0,68767		
3	AFL-8-350	0,12823 + j 0,71249		
4	AFL-8-525 (line 400 kV)	0,10357 + j 0,70020		
5	AFL-6-25	1,18235 + j 0,82786		
6	AFL-6-240	0,16817 + j 0,72463		
7	AFL-1,7-50 (ground cond.)	0,61650 + j 0,78787		

Impedance of a circuit with ground return

For numerical computation of the impedance of a circuit with ground return we have chosen a few types of two-layer conductors, and the computation results are presented in Table.

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