## Renormalization the Tensor Model of the Info-Communication Network

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*Abstract* - **Renormalization technique provided for the tensor model of the object interaction in the open info-communication network based on the least action principle.** 

*Keywords* – **Object interaction, info-communication network, tensor renormalization.** 

The tensor math modeling is an actual issue in the sphere of info-communications [1], [2]. However, the network tensor analysis needs further development. *The objective of this work is to determine renormalization technique for the tensor model of the open info-communication network based on the least action principle*.

Let  $P(n,m) = \{p_{nm}\}, n = 0,1,2,...,N -$  non-directed matrix graph of the open network built on the open set of vertices  $X = \{x_n\}$ ;  $p_{nm} = p(x_n, x_m) = p_{mn} = p(x_m, x_n)$  – nonnegative real numbers;  $x_0$  is open zero element of *X*. The non-diagonal elements  $p_{nm} = p_{mn}$ ,  $n \neq m$ ;  $n, m = 0,1,...,N$  are internal and the diagonal elements  $p_{nn} = p_n = p(x_n)$ ,  $n = 0,1,2,...,N$  are external interaction edges of vertices.

We want to determine a Riemann metric tensor  $R(P) = \{r_{nm}\}\$ as a function of *P*, where *R* is a real symmetric positively defined matrix, that meets the following requirements: all the non-diagonal elements of *R* and *P* are equal:  $r_{nm} = p_{nm}$ ,  $n \neq m$ ; all the diagonal elements of *R* satisfy the inequality  $r_{nn} \geq p_{nn}$ . Let  $x = \{x_n\}$ ,  $n = 0,1,2,...,N$ ;  $r(x) = r(x_n) = r_n$  is unknown vector of a posterior estimation for the matrix *R* diagonal elements;  $\zeta(x) = \zeta(x_n) = \zeta_n - a$ prior defined value of  $r(x)$ ;  $q(x) = q(x_n) = q_n$  the measured value of  $r(x)$  obtained from the matrix *P* as following:  $q_n = q(P) = \sum_{m=0}^{N} p_{nm}$ .

We formulate the principle of least action due to the following lagrangian  $L(x, r(x), a)$ :

$$
L(x, \rho(x), \alpha) = [\rho(x) - \vartheta_{\alpha}(x)]^{2};
$$
  
\n
$$
\rho(x) = \sqrt{r(x)};
$$
  
\n
$$
\vartheta_{\alpha}(x) = \sqrt{g_{\alpha}(x)};
$$
  
\n
$$
g_{\alpha}(x) = \frac{\widetilde{g}_{\alpha}(x)}{\int \widetilde{g}_{\alpha}(x)};
$$
  
\n
$$
\widetilde{g}_{\alpha}(x) = \frac{q(x) + \alpha \zeta(x)}{1 + \alpha \zeta(x)};
$$
  
\n
$$
0 < \alpha < \infty.
$$

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The variable factor  $\alpha$  generates a family of  $\tilde{g}(x)_{\alpha}$  performing the smooth transition of  $\tilde{g}_{\alpha}(x)$  from the  $q(x)$  function (if  $\alpha \rightarrow 0$ ) to the  $\zeta(x)$  function (if  $\alpha \rightarrow \infty$ ).

The least action principle for the lagrangian *L* means [3]:

$$
S(\rho, \alpha) = \int L(x, \rho(x), \alpha) dx = \min.
$$
 (1)

This turns to the variance optimization task [3]:

$$
\delta S(\rho, \alpha) = 0. \tag{2}
$$

The variance task Eq. (2) results the Euler equation that formulates the necessary condition of an extrema for the Eq.(1), [3]:

$$
\frac{\partial L}{\partial \rho} - \frac{d}{dx} \cdot \frac{\partial L}{\partial \rho} = 0,
$$
\n
$$
\rho = \frac{d\rho(x)}{dx}.
$$
\nIn our case  $\frac{\partial L}{\partial \rho} = 0$ ;  $\frac{\partial L}{\partial \rho} = 2\rho(x) - 2\vartheta_{\alpha}(x)$ .

Therefore,  $\rho(x) = \vartheta_{\alpha}(x)$ , or  $r(x) = g_{\alpha}(x)$ . Now, we put the  $r(x) = g_\alpha(x)$  vector into the main diagonal of matrix *R*. It results a family  ${R_\alpha}$  of tensors  $R(P,\alpha)$ . To select a subset  $(R_{\alpha}) \subseteq \{R_{\alpha}\}\$  of "good candidates" for the final solution of the variance task Eq. (1) we inspect the spectrum family  $\lambda_{\alpha}$  of Eigen values of  $R_\alpha$  tensor's family. The decision criteria is  $(\lambda_{\alpha})_{\min} \ge \varepsilon$ , where  $\varepsilon$  is predefined critically minimal positive value of  $\lambda_{\alpha}$ . The subset  $(R_{\alpha}) \subseteq \{R_{\alpha}\}\$  presents the limited number of tensors that consider "good candidates" for the final choice. The tensors  $R_{\alpha} \in (R_{\alpha})$  satisfy the requirements of Riemann metric tensor [3].

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